### **Proposed Program Structure for BE Automation and Robotics**

# Proposed Program Structure for Second Year Automation and Robotics (With Effect from 2023-2024) Scheme for Semester- III

| Course code | Course Name                     | Teaching S | t Hours) |    |
|-------------|---------------------------------|------------|----------|----|
|             |                                 | TH         | PR       | TU |
|             | Applied Mathematics-III         | 3          | -        | 1* |
|             | Strength of Material            | 4          | -        |    |
|             | Electronics Devices and Signal  |            |          |    |
|             | Conditioning                    | 3          |          | _4 |
|             | Digital Electronics             | 3          |          |    |
|             | Transducers                     | 4          |          |    |
|             | Transducers-I Lab               |            | 2        |    |
|             | Electronics Devices and Signal  |            |          | 7  |
|             | Conditioning Lab                |            | 2        |    |
|             | Digital Electronics - Lab       | . 1        | 2        |    |
|             |                                 |            |          |    |
|             | Object oriented programming Lab | -          | 3#       |    |
|             | Mini Project                    |            | 3\$      |    |

\$ indicates work load of Learner (Not Faculty), for Mini Project # Out of 3 hours, 1 hours theory shall be taught to entire class and 2 hours practical in batches

#### **Scheme for Semester- IV**

| Course code | Course Name                    | Teaching Scheme (Contact Hours) |     |    |
|-------------|--------------------------------|---------------------------------|-----|----|
|             |                                | TH                              | PR  | TU |
|             | Engineering Mathematics -IV    | 3                               |     | 1  |
|             | Embedded System                | 4                               |     |    |
|             | Feedback Control System        | 3                               |     |    |
|             | Fuild Pneumatics and Hydralics | 3                               |     |    |
|             | Control System                 |                                 |     |    |
|             | Components                     | 4                               |     |    |
|             | Embedded System - Lab          |                                 | 2   |    |
|             | Fuild Pneumatics and Hydralics |                                 |     |    |
|             | and Control System             |                                 |     |    |
|             | Components Lab                 |                                 | 2   |    |
|             | Feedback Control System - Lab  | 1                               | 2   |    |
|             | Python Programming-Lab         | 1                               | 2   |    |
|             | Mini Project                   |                                 | 4\$ |    |

### Proposed Program Structure for Third Year Automation and Robotics (With Effect from 2024-2025)

#### Scheme for Semester- V

| Course code | Course Name                         | Teaching Scheme (Contact Hours) |      |    |
|-------------|-------------------------------------|---------------------------------|------|----|
|             |                                     | TH                              | PR   | TU |
|             | Power Electronics and Machines      | 3                               |      |    |
|             | Robotic Control system              | 3                               |      |    |
|             | Robot Kinematics                    | 3                               | -    |    |
|             | Process Instrumentation and Data of | 3                               | -    |    |
|             | Department Elective-1               | 3                               |      | 4  |
|             | Robot Kinematics and                |                                 |      |    |
|             | Robotic Control Lab                 |                                 | 2    |    |
|             | Power Electronics and Machines      |                                 |      |    |
|             | Lab                                 |                                 | 2    |    |
|             | Process Instrumentation             |                                 |      |    |
|             | and Data communication Lab          |                                 | 2    |    |
|             | Professional Communication and      | 1                               |      |    |
|             | Ethics Lab                          | A                               | 2*+2 |    |
|             | Mini Project                        |                                 | 4\$  |    |

<sup>\*</sup> Theory class to be conducted for full class \$ indicates workload of Learner (Not Faculty), for Mini Project

#### Scheme for Semester- VI

| Course code | Course Name                    | Teaching Scheme (Contact Hours) |     |    |
|-------------|--------------------------------|---------------------------------|-----|----|
|             |                                | TH                              | PR  | TU |
|             | Process and Robotic Automation | 3                               |     |    |
|             | Digital Signal Processing      | 3                               |     |    |
|             | Machine Learning               | 3                               |     |    |
|             | Department Elective-2          | 3                               |     |    |
|             | Process and Robotic Automation |                                 |     |    |
|             | Lab                            |                                 | 2   |    |
|             | Digital Signal Processing and  |                                 |     |    |
|             | Machine Learning Lab           |                                 | 2   |    |
|             | 3D Printing                    |                                 | 4#  |    |
|             | Mini Project                   |                                 | 4\$ |    |

\$ indicates work load of Learner (Not Faculty), for Mini Project # Out of 3 hours, 1 hours theory shall be taught to entire class and 2 hours practical in batches

## Proposed Program Structure for Final Year Automation and Robotics (With Effect from 2025-2026)

### **Scheme for Semester- VII**

| Course code | Course Name                    | Teaching Scheme (Contact Hours) |    |    |
|-------------|--------------------------------|---------------------------------|----|----|
|             |                                | TH                              | PR | TU |
|             | Industrial Process Control     | 3                               | -  |    |
|             | Real Time Operating System     | 3                               |    |    |
|             | Image Processing               | 3                               | -  |    |
|             | Department Elective-3          | 3                               |    | _  |
|             | Institute Elective             |                                 |    |    |
|             | Industrial Process Control Lab |                                 | 2  |    |
|             | Real Time Operating System     |                                 |    |    |
|             | and Image Processing Lab       |                                 | 2  |    |
|             | Department Elective Lab-3      |                                 | 2  |    |
|             | Project-I                      |                                 |    |    |

### Scheme for Semester- VIII

| Course code | Course Name           | Teaching Scheme (Contact Hours) |    |    |
|-------------|-----------------------|---------------------------------|----|----|
|             |                       | TH                              | PR | TU |
|             | Machine Vision        | 3                               | -  |    |
|             | Mobile Robotics       | 3                               | -  |    |
|             | Department Elective-4 | 3                               | -  |    |
|             | Institute Elective    | 3                               |    |    |
|             | Machine Vision Lab    |                                 | 2  |    |
|             | Mobile Robotics Lab   |                                 | 2  |    |
|             | Project-II            |                                 | 2  |    |